

iC-JE

PWM RELAY/SOLENOID DRIVER



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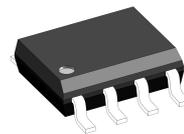
FEATURES

- ◆ Wide operating voltage range of 10 to 45 Vdc
- ◆ PWM control for coil currents of 40 to 300 mA
- ◆ Coil current for energise and hold modes set by an external resistor
- ◆ Coil current monitored during energise mode, detection of load breakage and voltage errors
- ◆ Automatic current reduction after 100 ms to reduce the power consumption in hold mode
- ◆ The internal free-wheeling alteration function supports PWM operation and quick demagnetising during shutdown
- ◆ Status signalled at the current-limited LED output
- ◆ Shutdown with excessive temperature and low voltage
- ◆ Integrated oscillator needs no external components
- ◆ PWM frequency is beyond audible range
- ◆ Protective circuitry against damage by ESD
- ◆ Minimum space requirements, few external components

APPLICATIONS

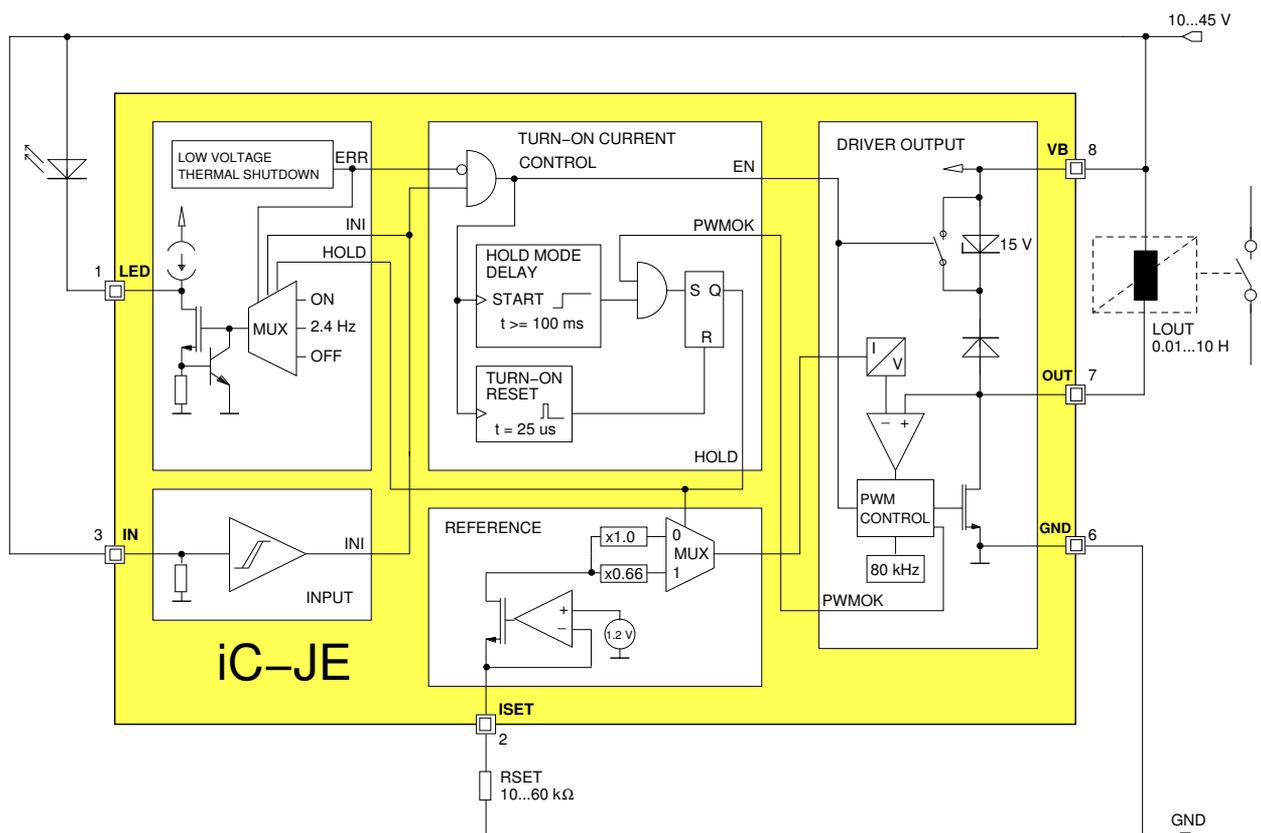
- ◆ PWM drive for inductive loads (e.g. relays, electrovalves)
- ◆ Relay low-/high-side switch

PACKAGES



SO8

BLOCK DIAGRAM



DESCRIPTION

iC-JE is a PWM driver for inductive loads, such as relay coils, solenoid valves and small DC motors.

The setpoint for the coil current is preset with the help of the RSET external resistor. 60 to 300 mA can be set for energise mode which then automatically drop to 2/3 of this value (40 to 200 mA) during hold mode. The device is switched to hold mode after 100 ms provided that the set coil current is obtained during energising (PWMOK = 1).

The changeover between energise and hold modes is suitable for typical relay drives which require a powerful initial energising current which can then be reduced after closing the air gap in a magnetic circuit. The quadratic dependence on the current intensity means that the power dissipation of the system is more than halved through this reduction.

The output current is measured with zero loss at the power transistor's ON resistance and compared to the setpoint. In order to maintain this setpoint, the

switch-on time of the coil driver is modulated by the pulse width. The internal flyback diode maintains the current during the switching pauses. The switching frequency of ca. 80 kHz is provided by the internal oscillator.

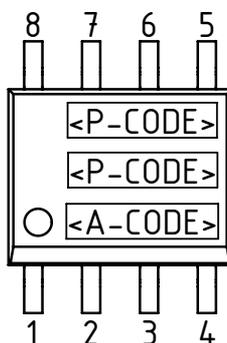
The device is shutdown by a Low signal at input IN or the removal of the power supply; the current reduction in the coil is supported by the changeover of the free-wheeling circuit. The Zener diode now active permits higher free-wheeling voltages and thus a quicker demagnetising of the coil.

The status indicator LED is constantly ON when hold mode is functioning correctly and flashes with low voltage, excessive temperature or when the coil current in energise mode has not reached the setpoint. The driver output is shutdown with low voltage or excessive temperature.

The device is protected against destruction by ESD.

PACKAGING INFORMATION SO8 to JEDEC

PIN CONFIGURATION SO8



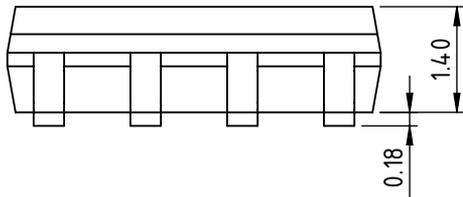
PIN FUNCTIONS

No. Name Function

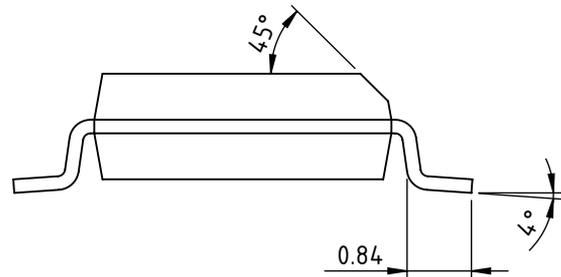
1	LED	State monitor
2	ISET	PWM Reference Current (setpoint adjustment)
3	IN	Input
4	n.c.	
5	n.c.	
6	GND	Ground
7	OUT	PWM Output
8	VB	+10 to 45 V Supply Voltage

PACKAGE DIMENSIONS SO8

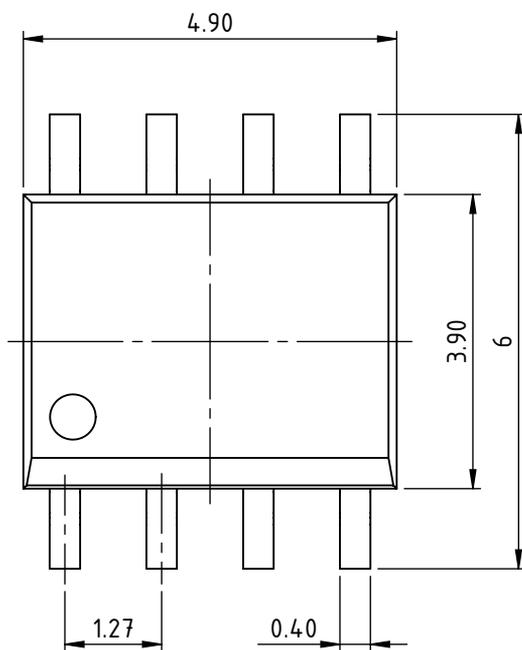
SIDE



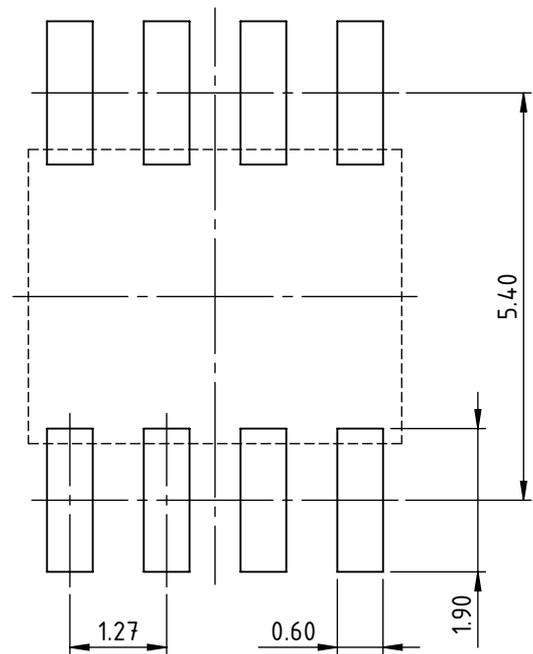
FRONT



TOP



RECOMMENDED PCB-FOOTPRINT



All dimensions given in mm. Tolerances of form and position according to JEDEC MS-012.

ABSOLUTE MAXIMUM RATINGS

Beyond these values damage may occur; device operation is not guaranteed.

Item No.	Symbol	Parameter	Conditions			Unit
				Min.	Max.	
G001	V(VB)	Voltage at VB		-0.3	48	V
G002	I(VB)	Current in VB		-350	6	mA
G003	V(OUT)	Voltage at OUT		-0.3	60	V
G004	I(OUT)	Output Current in OUT		-6	350	mA
G005	V(LED)	Voltage at LED		-0.3	VB	V
G006	I(LED)	Current in LED		-6	8	mA
G007	V(ISET)	Voltage at ISET		-0.3	48	V
G008	I(ISET)	Current in ISET		-6	6	mA
G009	V(IN)	Voltage at IN		-0.3	48	V
G010	I(IN)	Current in IN		-6	6	mA
G011	T _j	Junction Temperature		-40	150	°C
G012	T _s	Storage Temperature		-40	150	°C

THERMAL DATA

Operating Conditions: VB = 10...45V, LOUT = 0.01...10H, RSET = 10...60kΩ

Item No.	Symbol	Parameter	Conditions				Unit
				Min.	Typ.	Max.	
T01	T _a	Operating Ambient Temperature Range		-25		80	°C
T02	R _{thja}	Thermal Resistance Chip/Ambient	SO8 package			140	K/W

All voltages are referenced to ground unless otherwise stated.

All currents flowing into the device pins are positive; all currents flowing out of the device pins are negative.

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PWM RELAY/SOLENOID DRIVER



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ELECTRICAL CHARACTERISTICS

Operating Conditions: $V_B = 10...45\text{ V}$, $L_{OUT} = 0.01...10\text{ H}$, $R_{SET} = 10...60\text{ k}\Omega$, $T_j = -25...125\text{ }^\circ\text{C}$, unless otherwise noted.
LED connected or pin LED linked to GND (via ca. $500\text{ }\Omega$ resistor or capacitor).

Item No.	Symbol	Parameter	Conditions				Unit
				Min.	Typ.	Max.	
Total Device							
001	V_B	Permissible Supply Voltage Range		10		45	V
002	$I(V_B)$	Supply Current in V_B	Outputs OUT, LED disabled	0.5		2	mA
003	$I(V_B)$	Supply Current in V_B	Output OUT enabled	0.5		3	mA
004	$V_c(\text{lo})$	Clamp Voltage lo at all Pins	$I(\text{lo}) = -4\text{ mA}$, other Pins open	-1.4		-0.3	V
005	$V_c(\text{hi})$	Clamp Voltage hi at V_B , IN, ISET	$I(\text{lo}) = 4\text{ mA}$, other Pins open	48	57		V
006	$V_c(\text{hi})$	Clamp Voltage hi at OUT	$I(\text{OUT}) = 4\text{ mA}$, other Pins open	60	71		V
007	$V_c(\text{hi})$	Clamp Voltage hi at LED vs. V_B	$V_c(\text{hi}) = V(\text{LED}) - V(V_B)$; $I(\text{LED}) = 4\text{ mA}$, other Pins open	0.3		1.4	V
Driver Output OUT							
101	$V_s(\text{lo})$	Saturation Voltage lo	$I(\text{OUT}) = 200\text{ mA}$ (see Fig. 1)		360	600	mV
102	$V_s(\text{lo})$	Saturation Voltage lo	$I(\text{OUT}) = 300\text{ mA}$ (see Fig. 1)		550	850	mV
103	PWMthi	Permissible Energising Current	see Fig. 1 Increased Energising Current by RC-circuit at ISET, Hold Current 200 mA max. (see Fig. 5, 6)			300 350	mA mA
104	PWMthi	Permissible Hold Current	see Fig. 1	40			mA
105	Isc()	Short-circuit Current	$V(\text{OUT}) = V_B$	0.6	1	1.7	A
106	$V_c(\text{hi})$	Clamp Voltage hi at PWM-Free-Wheeling	$V_c(\text{hi}) = V(\text{OUT}) - V_B$; IN = hi, $I(\text{OUT}) = 200\text{ mA}$ (see Fig. 1)		1	1.5	V
107	$V_c(\text{hi})$	Clamp Voltage hi at PWM-Free-Wheeling	$V_c(\text{hi}) = V(\text{OUT}) - V_B$; IN = hi, $I(\text{OUT}) = 300\text{ mA}$ (see Fig. 1)		1.4	2	V
108	$V_c(\text{off})$	Clamp Voltage hi at Turn-off	$V_c(\text{hi}) = V(\text{OUT}) - V_B$; IN: hi \rightarrow lo, $I(\text{OUT}) = 200\text{ mA}$ (see Fig. 1)	12	15	17	V
109	I _{IK} ()	Leakage Current	IN = lo, $V(\text{OUT}) = 0...V_B$		1	10	μA
110	twon()min	Minimum PWM Turn-on Duration	IN = hi, ISET open (see Fig. 1)	250		1000	ns
111	C()	Permissible Load Capacitance				1	nF
Input IN							
201	$V_t(\text{on})$	Threshold Voltage hi		2.6	2.85	3.2	V
202	$V_t(\text{off})$	Threshold Voltage lo		1.7	2.0	2.3	V
203	$V_t(\text{hys})$	Hysteresis	$V_t(\text{hys}) = V_t(\text{on}) - V_t(\text{off})$	0.7	0.85	1.1	V
204	I _{pd} ()	Pull-down Current	$V(\text{IN}) = 4...45\text{ V}$	50	100	200	μA
205	R _{pd} ()	Pull-down Resistor	$V(\text{IN}) = 0...4\text{ V}$	20	50	80	k Ω
206	tp(IN-OUT)	Turn-on Delay	IN: lo \rightarrow hi			20	μs
207	tp(IN-OUT)	Turn-off Delay	IN: hi \rightarrow lo			10	μs
208	tp(VB-OUT)	Turn-on Delay when V_B is powered up	IN = VB, VB = V _{Boff} \rightarrow V _{Bon}			40	μs
209	tp(IN-LED)	Delay Time from IN to LED (with light permanently on)	PWMOK = 1 before tp _{PMWlo}	65	100	135	ms
210	tp(IN-LED)	Delay Time from IN to LED (with light flashing)	PWMOK = 0	130	200	270	ms
Status Monitor LED							
301	I _{pd} ()	Pull-down Current	$V(\text{LED}) = 5\text{ V}...V_B$	3	5	8	mA
302	$V_s(\text{lo})$	Saturation Voltage lo	$I(\text{LED}) = 200\text{ }\mu\text{A}$			0.4	V
303	I _{pu} ()	Pull-up Current	$V(\text{LED}) = 0\text{ V}... (V_B - 1\text{ V})$	-300	-100	-20	μA
304	V _{Blo}	Permissible Supply Voltage for Monitoring Function		6		45	V
305	V _{Bon}	Turn-on Threshold at V_B		7.6	8	8.4	V
306	V _{Boff}	Undervoltage Threshold at V_B	Decreasing voltage V_B	7.1	7.5	7.9	V
307	V _{Bhys}	Hysteresis	$V_{Bhys} = V_{Bon} - V_{Boff}$	200	500	800	mV
308	T _{off}	Thermal Shutdown Temperature		130	140	150	$^\circ\text{C}$
309	T _{on}	Thermal Lock-on Threshold	Decreasing temperature	110	120	130	$^\circ\text{C}$

ELECTRICAL CHARACTERISTICS

Operating Conditions: $V_B = 10...45\text{ V}$, $L_{OUT} = 0.01...10\text{ H}$, $R_{SET} = 10...60\text{ k}\Omega$, $T_J = -25...125\text{ }^\circ\text{C}$, unless otherwise noted.
LED connected or pin LED linked to GND (via ca. $500\text{ }\Omega$ resistor or capacitor).

Item No.	Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
310	Thys	Thermal Shutdown Hysteresis	$\text{Thys} = \text{Toff} - \text{Ton}$	10	20	30	$^\circ\text{C}$
311	f()	Flash Frequency on Error	$\text{ERR} = \text{hi}$ or $\text{PWMOK} = 0$, $V_B = 6...45\text{ V}$	1.8	2.4	3.6	Hz
Reference ISET							
401	V()	Reference Voltage		1.14	1.20	1.26	V
402	Isc()	Short-Circuit Current	$V(\text{ISET}) = 0\text{ V}$	-3.0	-1.8	-0.3	mA
403	K1	Transfer Value for Energising Current $R_{SET} = K1 / I(\text{OUT})_{\text{start}}$	$I(\text{OUT})_{\text{start}} = 60...300\text{ mA}$ (see Fig. 1)	2900	3400	3900	$\text{A}\Omega$
404	CRrel	Relative Current Ratio $I_t(\text{OUT})_{\text{hold}} / I_t(\text{OUT})_{\text{start}}$ (Trigger Thresholds Ratio: Hold vs. Energise Mode)	$I(\text{OUT})_{\text{start}} = 60...300\text{ mA}$ (see Fig. 1)	63	66	71	%
405	K2	Transfer Value for Hold Current $R_{SET} = K2 / I(\text{OUT})_{\text{hold}}$	$I(\text{OUT})_{\text{hold}} = 40...200\text{ mA}$	1930	2315	2700	$\text{A}\Omega$
Oscillator							
501	fosc	Oscillator Frequency	see Fig. 1	60	80	120	kHz
Turn-on Current Control							
601	tpPWMlo	Hold Mode Propagation Delay	$\text{PWMOK} = 1$ before t_{pPWMlo}	65	100	135	ms

ELECTRICAL CHARACTERISTICS: Diagrams

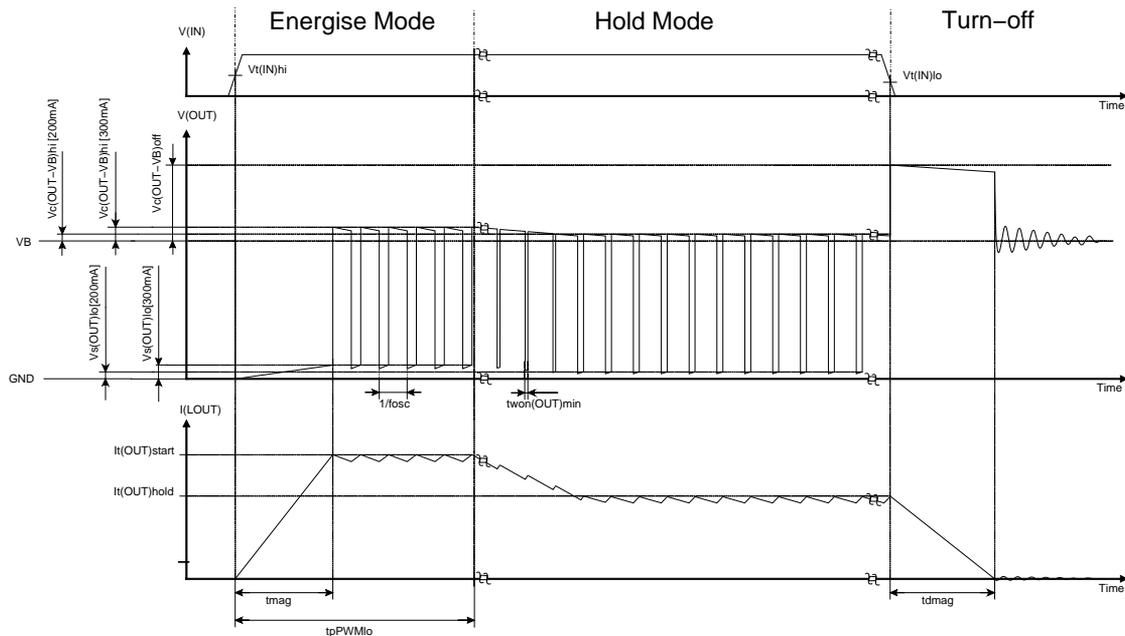


Figure 1: Operation modes: energise mode, hold mode and turn-off

$$t_{\text{mag}} \approx \frac{I_t(\text{OUT})_{\text{start}} \times L_{\text{OUT}}}{V_B} \quad (1)$$

$$t_{\text{dmag}} \approx \frac{I_t(\text{OUT})_{\text{hold}} \times L_{\text{OUT}}}{V_c(\text{OUT} - V_B)_{\text{hi}}} \quad (2)$$

APPLICATIONS INFORMATION

Setting the coil current

The following equations can be given for the energise and hold modes of the PWM control using Electrical Characteristics Nos. 403 to 405:

$$RSET = \frac{K1}{I(OUT)_{start}} \quad (3)$$

$$RSET = \frac{K2}{I(OUT)_{hold}} \quad (4)$$

Example

For a relay with a energising current of 100 mA (66 mA hold current) RSET is calculated as:

$$RSET = \frac{3250 \Omega A}{0.1 A} = 32.5 k\Omega \quad (5)$$

Application circuits

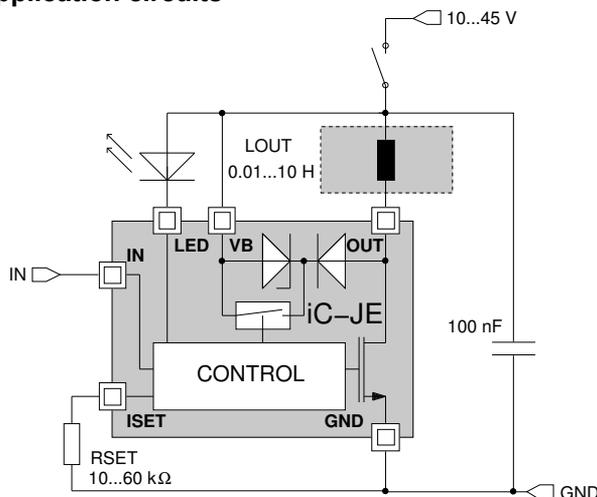


Figure 2: Driver/relay combination activated via the external control input IN

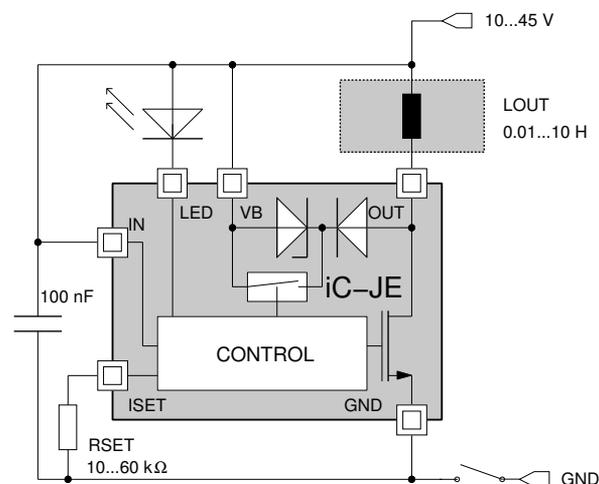


Figure 3: Driver/relay combination activated via the supply pin GND

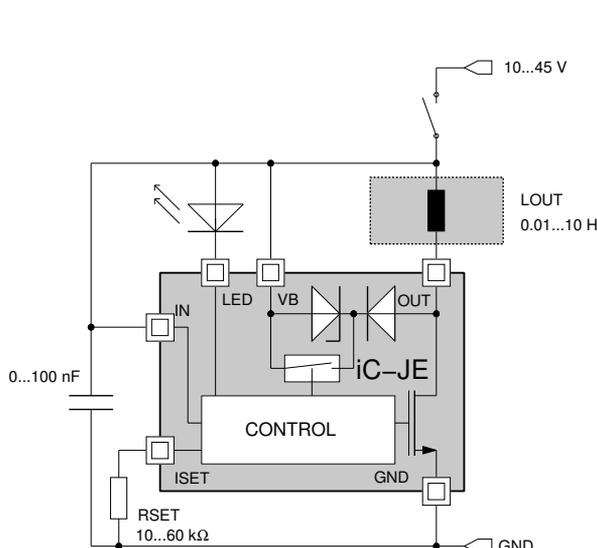


Figure 4: Driver/relay combination activated via the supply pin VB

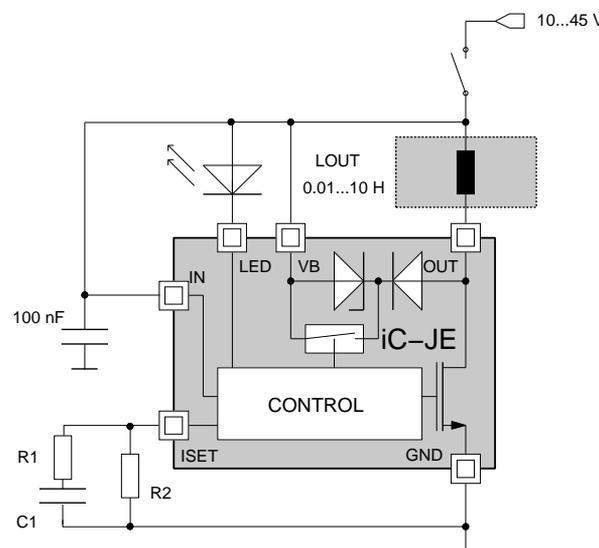


Figure 5: Increased energizing current due to the parallel RC-circuit

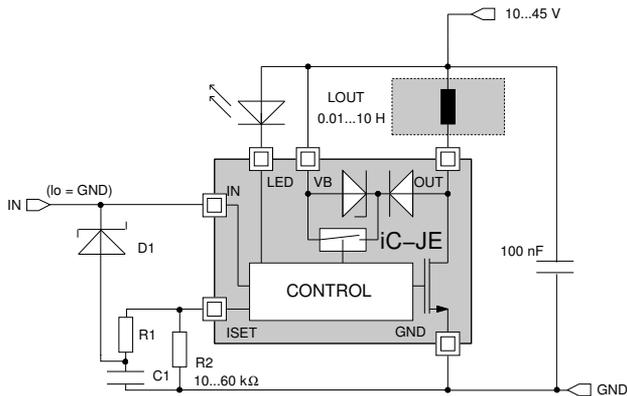


Figure 6: Activation via pin IN with an increased energizing current. An additional Schottky diode discharges C1 if IN is switched to low (GND)

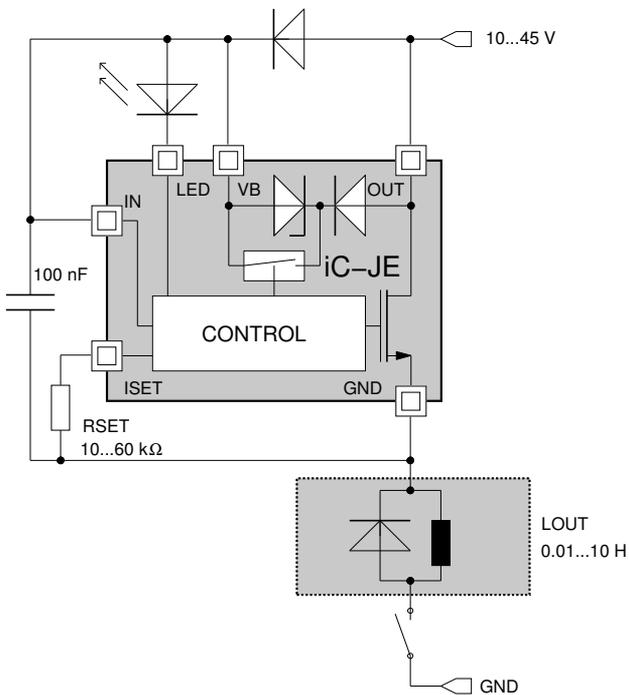


Figure 7: High-side driver for an external relay with a flyback diode

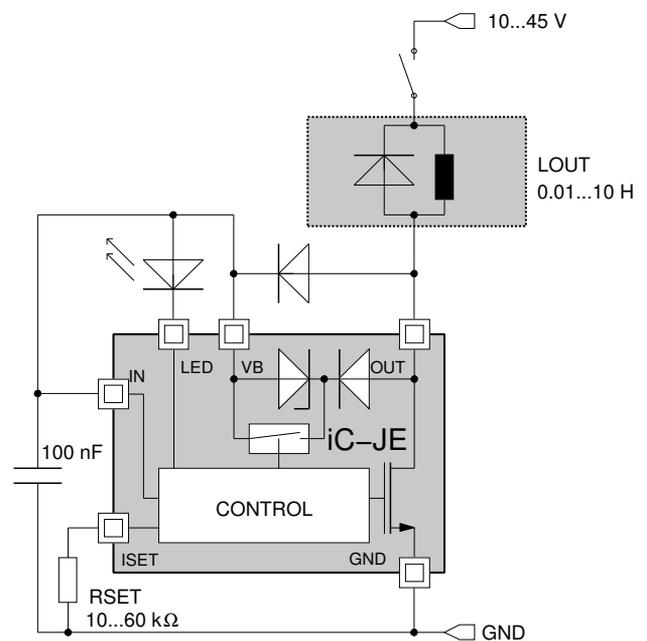


Figure 8: Low-side driver for an external relay with a flyback diode

EVALUATION BOARD

The iC-JE is equipped with a Evaluation Board for test purposes. The following figures show the circuit diagram as well as the top and bottom layout of the test PCB.

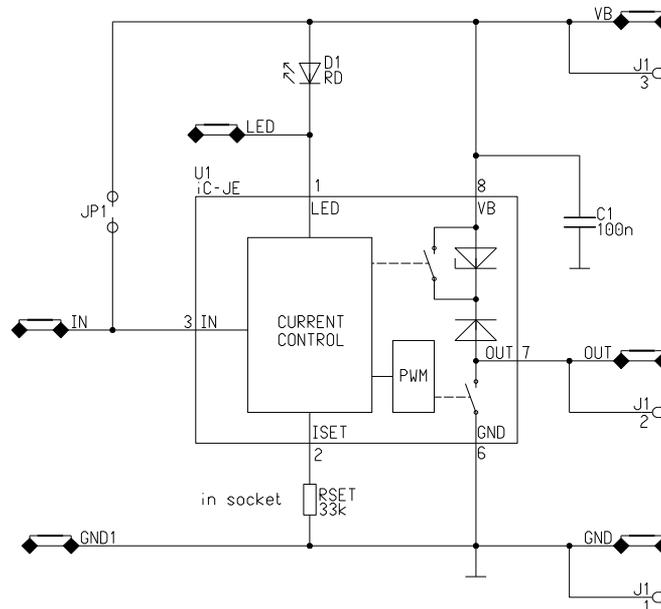


Figure 9: Schematic diagram of the Evaluation Board

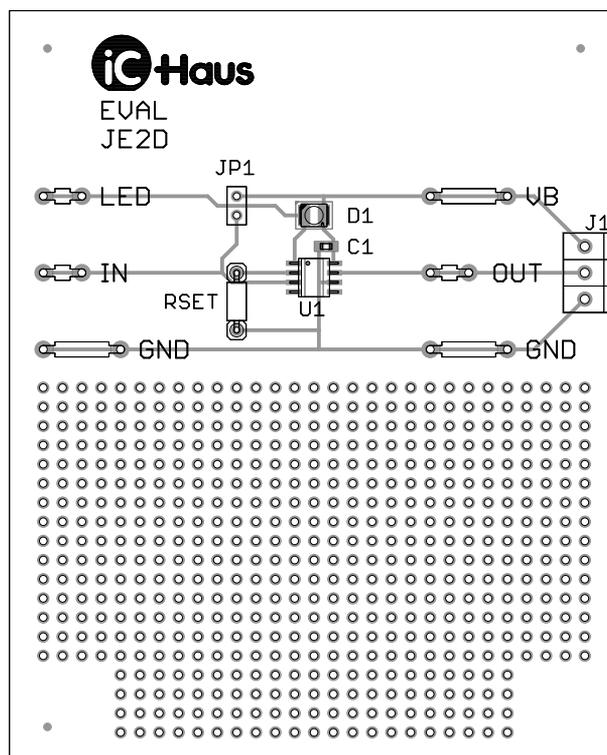


Figure 10: Evaluation Board (components side)

iC-JE

PWM RELAY/SOLENOID DRIVER



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REVISION HISTORY

Rel	Rel.Date	Chapter	Modification	Page
G3	15-02-23		DIP8 package discontinued	1-2, 4, 11
		PACKAGING INFORMATION	Dimensions and Footprint added for SO8	3

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ORDERING INFORMATION

Type	Package	Order Designation
iC-JE	SO8	iC-JE SO8
	Evaluation Board	iC-JE EVAL JE2D

For technical support, information about prices and terms of delivery please contact:

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